

A new class of continuous functions via δ gp-open sets in topological spaces

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Abstract

In this paper, a new class of almost continuity called almost δ gp-continuity is presented. Characterizations and properties of almost δ gp-continuous functions are discussed.

1 Introduction

The notion of continuity on topological spaces, as significant and fundamental subject in the study of topology, has been researched by many mathematicians. Several investigations related to almost continuity which is a generalization of continuity have been published. The study of almost continuity was initiated by Singal and Singal [29] in 1968. Almost pre-continuous functions were introduced and investigated by Nasef and Noiri [22]. In this paper, we define and study the notion of almost δ gp-continuous functions which is stronger than the notion of almost gpr-continuous functions [4]. Also, we obtain various characterizations of almost δ gp-continuous functions and investigate some of their fundamental properties.

Throughout this paper, (X, τ) , (Y, σ) and (Z, η) (or simply X, Y and Z) represent topological spaces on which no separation axioms are assumed unless explicitly stated and $f : (X, \tau) \rightarrow (Y, \sigma)$ or simply $f : X \rightarrow Y$ denotes a function

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f of a topological space X into a topological space Y . Let $M \subseteq X$, then $cl(M) = \bigcap \{F : M \subseteq F \text{ and } F^c \in \tau\}$ is the closure of M . Also, $\text{int}(M) = \bigcup \{O : O \subseteq M \text{ and } O \in \tau\}$ is the interior of M .

The class of δ gp-open (resp. δ gp-closed, open, closed, regular open, regular closed, δ -preopen, δ -semiopen, e^* -open, preopen, semiopen and β -open) sets of (X, τ) containing a point $p \in X$ is denoted by δ GPO(X, p)(resp. δ GPC(X, p), $O(X, p)$, $C(X, p)$, $RO(X, p)$, $RC(X, p)$, δ PO(X, p), δ SO(X, p), $e^*O(X, p)$, $PO(X, p)$, $SO(X, p)$ and $\beta O(X, p)$).

2 Preliminaries

Definition 2.1. A set $M \subseteq X$ is called pre-closed [21] (resp. regular-closed [31], semi-closed [19], β -closed [1]) if $cl(\text{int}(M)) \subseteq M$ (resp. $M = cl(\text{int}(M))$, $\text{int}(cl(M)) \subseteq M$ and $\text{int}(cl(\text{int}(M))) \subseteq M$).

Definition 2.2. A set $M \subseteq X$ is called δ -closed [35] if $M = cl_\delta(M)$ where $cl_\delta(M) = \{p \in X : \text{int}(cl(N)) \cap M \neq \phi, N \in \tau \text{ and } p \in N\}$.

Definition 2.3. A set $M \subseteq X$ is called δ -preclosed [26] (resp. e^* -closed [13], δ -semiclosed [25] and a -closed [14]) if $cl(\text{int}_\delta(M)) \subseteq M$ (resp. $\text{int}(cl(\text{int}_\delta(M))) \subseteq M$, $\text{int}(cl_\delta(M)) \subseteq M$ and $cl(\text{int}(cl_\delta(M))) \subseteq M$).

Definition 2.4. A set $M \subseteq X$ is called:

- (i) δ gp-closed [7] (resp. gpr-closed [17] and gp-closed [20]) if $pcl(M) \subseteq G$ whenever $M \subseteq G$ and G is δ -open (resp. regular open and open) in X ,
- (ii) $g\delta s$ -closed [5] if $scl(M) \subseteq G$ whenever $M \subseteq G$ and G is δ -open in X .

The complements of the above mentioned closed sets are their respective open sets .

Definition 2.5. A function $f : X \rightarrow Y$ is called:

- (i) R -map [9] (resp. δ -continuous [23], almost continuous [29], almost pre-continuous [22], almost gp-continuous, almost gpr-continuous [4] and almost $g\delta s$ -continuous [6]) if the inverse image of every regular open set G of Y is regular open (resp. δ -open, open, pre-open, gp-open, gpr-open and $g\delta s$ -open) in X ,
- (ii) δ gp-continuous [32] if the inverse image of every open set G of Y is δ gp-open in X ,

- (iii) almost contra continuous [3](resp. almost contra super-continuous [11] and contr R -map [10]) if the inverse image of every regular closed set G of Y is open (resp. δ -open and regular open) in X ,
- (iv) almost perfectly-continuous [30]) if the inverse image of every regular closed set G of Y is clopen in X ,
- (v) almost contra δ gp-continuous [34](resp. contra δ gp-continuous [33] and δ gp-irresolute [32]) if the inverse image of every regular open (resp. open and δ gp-closed) set G of Y is δ gp-closed in X .

Definition 2.6. A space X is said to be:

- (i) preregular $T_{\frac{1}{2}}$ -space [16] if $GPRO(X) = PO(X)$,
- (ii) $T_{\delta gp}$ -space [7] if $\delta GPO(X) = O(X)$,
- (iii) $\delta gp T_{\frac{1}{2}}$ -space [7] if $\delta GPO(X) = PO(X)$,
- (iv) extremely disconnected [16] if the closure of every open subset of X is open,
- (v) submaximal [27] if every pre-open set is open,
- (vi) strongly irresolvable [15] if every open subspace of X is irresolvable,
- (vii) nearly compact [28] if every regular open cover of X has a finite subcover,
- (viii) r - T_1 -space [12] if for each pair of distinct points x and y of X , there exist regular open sets U and V such that $x \in U$, $y \notin U$ and $x \notin V$, $y \in V$,
- (ix) r - T_2 -space [12] if for each pair of distinct points x and y of X , there exist regular open sets U and V such that $x \in U$, $y \in V$ and $U \cap V = \phi$,
- (x) δgp - T_1 -space [34] if for any pair of distinct points p and q , there exist $G, H \in \delta GPO(X)$ such that $p \in G$, $q \notin G$ and $q \in H$, $p \notin H$,
- (xi) δgp -Hausdorff space [33] if for each pair of distinct points x and y of X , there exist $G, H \in \delta GPO(X)$ such that $x \in G$, $y \in H$ and $G \cap H = \phi$,
- (xii) δgp -additive [33] if $\delta GPC(X)$ is closed under arbitrary intersections.

Definition 2.7. [8] A subset M of a space X is said to be N -closed relative to X if every cover of M by regular open sets of X has a finite subcover.

Theorem 2.1. [33] (i) If A and B are δgp -open subsets of a submaximal space X , then $A \cap B$ is δgp -open in X .

(ii) Let X be a δgp -additive space. Then $A \subseteq X$ is δgp -closed if and only if $\delta gp-cl(A) = A$.

Definition 2.8. [18] A space X is called locally indiscrete if $O(X) = RO(X)$.

Lemma 2.1. [24, 33] Let (X, τ) be a space and let A be a subset of X . The following statements are true:

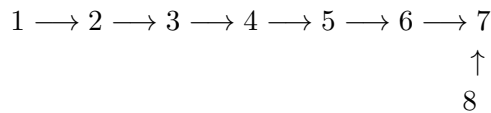
- (i) $A \in PO(X)$ if and only if $scl(A) = int(cl(A))$.
(ii) $p \in \delta gpcl(A)$ if and only if $U \cap A \neq \emptyset$ for every δgp -open set U containing p .

3 Almost δgp -Continuous Functions.

Definition 3.1. A function $f: X \rightarrow Y$ is called almost δgp -continuous if $f^{-1}(N) \in \delta GPC(X)$ for each regular closed set N of Y .

Theorem 3.1. A function $f: X \rightarrow Y$ is almost δgp -continuous if and only if the inverse image of every regular open set of Y is δgp -open in X .

Remark 3.1. From Definitions 2.5 and 3.1, we have the following diagram for a function $f: X \rightarrow Y$:



Notations:

- 1- R-map; 2- δ -continuity; 3-almost continuity; 4-almost pre continuity;
5- almost gp -continuity; 6-almost δgp -continuity; 7-almost gpr -continuity;
8- δgp -continuous.

None of these implications is reversible.

Example 3.1. Let $X = \{p, q, r, s\} = Y$, $\tau = \{X, \emptyset, \{p\}, \{q\}, \{p, q\}, \{p, q, r\}\}$ and $\sigma = \{Y, \emptyset, \{p\}, \{q\}, \{p, q\}, \{p, r\}, \{p, q, r\}\}$. Define $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(p) = f(r) = q$, $f(q) = p$ and $f(s) = r$. Clearly f is almost δgp -continuous but for $\{q\} \in RO(Y)$, $f^{-1}(\{q\}) = \{p, r\} \notin GPO(X)$. Therefore f is not almost gp -continuous. Define $g: (X, \tau) \rightarrow (Y, \sigma)$ by $g(p) = p$, $g(q) = s$, $g(r) = r$ and $g(s) = q$. Then g is almost δgp -continuous but for $\{p\} \in O(Y)$, $g^{-1}(\{p\}) = \{p\} \notin \delta GPO(X)$. Therefore g is not δgp -continuous. Define $h: (X, \tau) \rightarrow (X, \sigma)$ by $h(p) = h(q) = q$, $h(r) = p$ and $h(s) = r$. Then h is almost gpr -continuous but for $\{q\} \in RO(Y)$, $h^{-1}(\{q\}) = \{p, q\} \notin \delta GPO(Y)$. Therefore h is not almost δgp -continuous.

Theorem 3.2. If $f: X \rightarrow Y$ is almost δgp -continuous and Y is locally indiscrete space, then f is δgp -continuous.

Proof. Let N be an open set in Y , then N is regular-open in Y . Since f is almost δ gp-continuous, then $f^{-1}(N)$ is δ gp-open in X . Hence f is δ gp-continuous \square

Theorem 3.3. *Let X be a locally indiscrete space, then the following properties are equivalent:*

- (i) $f: X \rightarrow Y$ is almost gpr-continuous;
- (ii) $f: X \rightarrow Y$ is almost δ gp-continuous;
- (iii) $f: X \rightarrow Y$ is almost gp-continuous.

Proof. Follows from the Theorem 3.7 of [34] \square

Theorem 3.4. (i) *If $f: X \rightarrow Y$ is almost $g\delta s$ -continuous with X as extremely disconnected space, then it is almost δ gp-continuous.*

(ii) *If $f: X \rightarrow Y$ is almost δ gp-continuous with X as strongly irresolvable space. Then it is almost $g\delta s$ -continuous.*

Proof. Follows from the Theorem 3.9 of [34]

As a consequence of Lemma 3.10 of [32], we have the following Theorem \square

Theorem 3.5. *The following statements are equivalent:*

- (i) $f: X \rightarrow Y$ is almost perfectly continuous;
- (ii) $f: X \rightarrow Y$ is almost contra continuous and almost pre-continuous;
- (iii) $f: X \rightarrow Y$ is almost contra continuous and almost gp-continuous;
- (iv) $f: X \rightarrow Y$ is almost contra super-continuous and almost δ gp-continuous;
- (v) $f: X \rightarrow Y$ is contra R -map and almost gpr-continuous;
- (vi) $f: X \rightarrow Y$ is contra R -map and almost pre-continuous;
- (vii) $f: X \rightarrow Y$ is almost contra super-continuous and almost pre-continuous.

Theorem 3.6. *Let X be a δ gp $T_{\frac{1}{2}}$ -space. Then the following are equivalent:*

- (i) $f: X \rightarrow Y$ is almost pre-continuous;
- (ii) $f: X \rightarrow Y$ is almost gp-continuous;

(iii) $f: X \rightarrow Y$ is almost δgp -continuous.

Theorem 3.7. Let X be a preregular $T_{\frac{1}{2}}$ -space. Then the following statements are equivalent:

(i) $f: X \rightarrow Y$ is almost pre-continuous;

(ii) $f: X \rightarrow Y$ is almost gp -continuous;

(iii) $f: X \rightarrow Y$ is almost δgp -continuous;

(iv) $f: X \rightarrow Y$ is almost gpr -continuous.

Theorem 3.8. Let X be a $T_{\delta gp}$ -space. Then the following are equivalent:

(i) $f: X \rightarrow Y$ is almost continuous;

(ii) $f: X \rightarrow Y$ is almost pre-continuous;

(iii) $f: X \rightarrow Y$ is almost gp -continuous;

(iv) $f: X \rightarrow Y$ is almost δgp -continuous;

(v) $f: X \rightarrow Y$ is almost gpr -continuous.

Theorem 3.9. The following are equivalent:

(i) $f: X \rightarrow Y$ is almost δgp -continuous and X is δgp -additive;

(ii) for each $p \in X$ and each open set N containing $f(p)$, there exists δgp -open set M containing p such that $f(M) \subset \text{int}(\text{cl}(N))$.

Proof. Obvious □

Theorem 3.10. The following statements are equivalent:

(i) $f: X \rightarrow Y$ is almost δgp -continuous and X is δgp -additive;

(ii) For each $p \in X$ and each $N \in \mathcal{O}(Y, f(p))$, there exists $M \in \delta GPO(X, p)$ such that $f(M) \subset \text{scl}(N)$;

(iii) For each $p \in X$ and each $H \in \mathcal{RO}(Y, f(p))$, there exists $G \in \delta GPO(X, p)$ such that $f(G) \subset H$;

(iv) For each $p \in X$ and each $V \in \delta \mathcal{O}(Y, f(p))$, there exists $U \in \delta GPO(X, p)$ such that $f(U) \subset V$;

(v) For each $p \in X$ and each $V \in \delta \mathcal{C}(Y, f(p))$, there exists $U \in \delta GPC(X, p)$ such that $f(U) \subset V$.

Proof. (i) \rightarrow (ii): Let $p \in X$ and N be an open set of Y containing $f(p)$. By (i) and Theorem 3.9, there exists $M \in \delta GPO(X, p)$ such that $f(M) \subset \text{int}(\text{cl}(N))$. Since M is preopen, then by Lemma 2.1(i), $f(M) \subset \text{scl}(N)$.

(ii) \rightarrow (iii): Let $p \in X$ and $N \in RO(Y, f(p))$. Then $N \in O(Y, f(p))$. By (ii), there exists $M \in \delta GPO(X, p)$ such that $f(M) \subset \text{scl}(N)$. Since H is preopen, then by Lemma 2.1(i), $f(M) \subset \text{int}(\text{cl}(N)) = N$.

(iii) \rightarrow (iv): Let $p \in X$ and $N \in \delta O(Y, f(p))$, then there exists $M \in O(X, f(p))$ such that $M \subset \text{int}(\text{cl}(M)) \subset N$. Since $\text{int}(\text{cl}(M)) \in RO(Y, f(p))$, by (iii), there exists $U \in \delta GPO(X, p)$ such that $f(U) \subset \text{int}(\text{cl}(M)) \subset N$.

(iv) \rightarrow (i): Let $p \in X$ and $N \in O(Y, f(p))$. Then $\text{int}(\text{cl}(N)) \in \delta O(Y, f(p))$.

By (iv), there exists $M \in \delta GPO(X, p)$ such that $f(M) \subset \text{int}(\text{cl}(N))$.

Hence f is almost δ gp-continuous.

(iv) \leftrightarrow (v): Obvious. □

Theorem 3.11. *Let X be a δ gp-additive space. Then $M \subseteq X$ is δ gp-closed (resp. δ gp-open) if and only if δ gp-cl(M)= M (resp. δ gp-int(M)= M).*

Theorem 3.12. *The following statements are equivalent:*

(i) $f: X \rightarrow Y$ is almost δ gp-continuous and X is δ gp-additive;

(ii) $f(\delta$ gp-cl(M)) \subset $cl_\delta(f(M))$ for each $M \subseteq X$;

(iii) δ gp-cl($f^{-1}(N)$) \subset $f^{-1}(cl_\delta(N))$ for each $N \subseteq Y$;

(iv) $f^{-1}(G) \in \delta GPC(X)$ for each $G \in \delta C(Y)$;

(v) $f^{-1}(H) \in \delta GPO(X)$ for each $H \in \delta O(Y)$.

Proof. (i) \rightarrow (ii) Suppose that $N \in \delta C(Y)$ such that $f(M) \subset N$. Observe that $N = cl_\delta(N) = \bigcap \{F : N \subset F \text{ and } F \in RC(Y)\}$ and so $f^{-1}(N) = \bigcap \{f^{-1}(F) : N \subset F \text{ and } F \in RC(Y)\}$. By (i) and Definition 2.6(xii), we have $f^{-1}(N) \in \delta GPC(X)$ and $M \subset f^{-1}(N)$. Hence δ gp-cl(M) \subset $f^{-1}(N)$, and it follows that $f(\delta$ gp-cl(M)) \subset N . Since this is true for any δ -closed set N containing $f(M)$, we have $f(\delta$ gp-cl(M)) \subset $cl_\delta(f(M))$.

(ii) \rightarrow (iii) Let $D \subset Y$, then $f^{-1}(D) \subset X$. By (ii),

$f(\delta$ gp-cl($f^{-1}(D)$)) \subset $cl_\delta(f(f^{-1}(D))) \subset \delta$ gp-cl(D). So that δ gp-cl($f^{-1}(D)$) \subset $f^{-1}(Cl_\delta(D))$.

(iii) \rightarrow (iv) Let $G \in \delta C(Y)$. Then by (iii), δ gp-cl($f^{-1}(G)$) \subset $f^{-1}(cl_\delta(G)) = f^{-1}(G)$.

In consequence, δ gp-cl($f^{-1}(G)$) = $f^{-1}(G)$ and hence by Theorem 3.11, $f^{-1}(G) \in \delta GPC(X)$.

(iv) \rightarrow (v): Clear.

(v) \rightarrow (i): Let $N \in RO(Y)$. Then $N \in \delta O(Y)$. By (v), $f^{-1}(N) \in \delta GPO(X)$. Hence by Theorem 3.1, f is almost δgp -continuous \square

Theorem 3.13. *The following statements are equivalent:*

- (i) $f: X \rightarrow Y$ is almost δgp -continuous and X is δgp -additive;
- (ii) For every $N \in O(Y)$, $f^{-1}(int(cl(N)) \in \delta GPO(X)$;
- (iii) For every $M \in C(Y)$, $f^{-1}(cl(int(M)) \in \delta GPC(X)$;
- (iv) For every $N \in \beta O(Y)$, $\delta gpcl(f^{-1}(N)) \subset f^{-1}(cl(N))$;
- (v) For every $M \in \beta C(Y)$, $f^{-1}(int(M)) \subset \delta gpint(f^{-1}(M))$;
- (vi) For every $M \in SC(Y)$, $f^{-1}(int(M)) \subset \delta gpint(f^{-1}(M))$;
- (vii) For every $N \in SO(Y)$, $\delta gpcl(f^{-1}(N)) \subset f^{-1}(cl(N))$;
- (viii) For every $M \in PO(Y)$, $f^{-1}(M) \subset \delta gpint(f^{-1}(int(cl(M)))$.

Proof. (i) \leftarrow (ii): Let $N \in O(Y)$. Since $int(cl(N)) \in RO(Y)$ Then by (i), $f^{-1}(int(cl(N))) \in \delta GPO(X)$. The converse is similar.

(i) \leftarrow (iii) It is similar to (i) \leftarrow (ii).

(i) \rightarrow (iv): Let $N \in \beta O(Y)$, then $cl(N) \in RC(Y)$ so by (i), $f^{-1}(cl(N)) \in \delta GPC(X)$. Since $f^{-1}(N) \subset f^{-1}(cl(N))$ which implies $\delta gpcl(f^{-1}(N)) \subset f^{-1}(cl(N))$.

(iv) \rightarrow (v) and (vi) \rightarrow (vii): Obvious

(v) \rightarrow (vi): It follows from the fact that $SC(Y) \subset \beta C(Y)$

(vii) \rightarrow (i): It follows from the fact that $RC(Y) \subset SO(Y)$.

(i) \leftarrow (viii): Let $N \in PO(Y)$. Since $int(cl(N)) \in RO(Y)$, then by (i),

$f^{-1}(int(cl(N))) \in \delta GPO(X)$ and hence

$f^{-1}(N) \subset f^{-1}(int(cl(N))) = \delta gpint(f^{-1}(int(cl(N))))$. Conversely, let $N \in RO(Y)$.

Since $N \in PO(Y)$, $f^{-1}(N) \subset \delta gp-int(f^{-1}(int(Cl(N)))) = \delta gpint(f^{-1}(N))$, in consequence, $\delta gpint(f^{-1}(N)) = f^{-1}(N)$ and by Theorem 3.11, $f^{-1}(N) \in \delta GPO(X)$. \square

Theorem 3.14. *The following are equivalent:*

- (i) $f: X \rightarrow Y$ is almost δgp -continuous and X is δgp -additive;
- (ii) For every e^* -open set N of Y , $f^{-1}(cl_\delta(N))$ is δgp -closed in X ;
- (iii) For every δ -semiopen subset N of Y , $f^{-1}(cl_\delta(N))$ is δgp -closed set in X ;
- (iv) For every δ -preopen subset N of Y , $f^{-1}(int(cl_\delta(N)))$ is δgp -open set in X ;
- (v) For every open subset N of Y , $f^{-1}(int(cl_\delta(N)))$ is δgp -open set in X ;
- (vi) For every closed subset N of Y , $f^{-1}(cl(int_\delta(N)))$ is δgp -closed set in X .

Proof. (i) \rightarrow (ii): Let $N \in e^*O(Y)$ Then by Lemma 2.7 of [2], $cl_\delta(N) \in RC(Y)$.

By (i), $f^{-1}(cl_\delta(N)) \in \delta GPC(X)$.

(ii) \rightarrow (iii): Obvious since $\delta\text{SO}(Y) \subset e^*\text{O}(Y)$.

(iii) \rightarrow (iv): Let $N \in \delta\text{PO}(Y)$, then $\text{int}_\delta(Y \setminus N) \in \delta\text{SO}(Y)$. By (iii), $f^{-1}(\text{cl}_\delta(\text{int}_\delta(Y \setminus N))) \in \delta\text{GPC}(X)$ which implies $f^{-1}(\text{int}(\text{cl}_\delta(N))) \in \delta\text{GPO}(X)$.

(iv) \rightarrow (v): Obvious since $\text{O}(Y) \subset \delta\text{PO}(Y)$.

(v) \rightarrow (vi): Clear

(vi) \rightarrow (i): Let $N \in \text{RO}(Y)$. Then $N = \text{int}(\text{cl}_\delta(N))$ and hence $(Y \setminus N) \in \text{C}(X)$. By (vi), $f^{-1}(Y \setminus N) = X \setminus f^{-1}(\text{int}(\text{cl}_\delta(N))) = f^{-1}(\text{cl}(\text{int}_\delta(Y \setminus N))) \in \delta\text{GPC}(X)$.

Thus $f^{-1}(N) \in \delta\text{GPO}(X)$. □

Theorem 3.15. *The following are equivalent for a function $f: X \rightarrow Y$:*

- (i) f is almost δ gp-continuous and X is δ gp-additive;
- (ii) For every e^* -open subset G of Y , $f^{-1}(a\text{-cl}(G))$ is δ gp-closed set in X ;
- (iii) For every δ -semiopen subset G of Y , $f^{-1}(\delta\text{-pcl}(G))$ is δ gp-closed set in X ;
- (iv) For every δ -preopen subset G of Y , $f^{-1}(\delta\text{-scl}(G))$ is δ gp-open set in X .

Proof. Follows from the Lemma 3.1 of [2] □

Theorem 3.16. *If $f: X \rightarrow Y$ is an almost δ gp-continuous injective function and Y is $r\text{-}T_1$, then X is δ gp- T_1 .*

Proof. Let (Y, σ) be $r\text{-}T_1$ and $p, q \in X$ with $p \neq q$. Then there exist regular open subsets G, H in Y such that $f(p) \in G$, $f(q) \notin G$, $f(p) \notin H$ and $f(q) \in H$. Since f is almost δ gp-continuous, $f^{-1}(G)$ and $f^{-1}(H) \in \delta\text{GPO}(X)$ such that $p \in f^{-1}(G)$, $q \notin f^{-1}(G)$, $p \notin f^{-1}(H)$ and $q \in f^{-1}(H)$. Hence X is δ gp- T_1 . □

Theorem 3.17. *If $f: X \rightarrow Y$ is an almost δ gp-continuous injective function and Y is $r\text{-}T_2$, then X is δ gp- T_2 .*

Proof. Similar to the proof of Theorem 3.16 □

Theorem 3.18. *If $f, g: X \rightarrow Y$ are almost δ gp-continuous with X as submaximal and δ gp-additive and Y is Hausdorff, then the set $\{x \in X : f(x) = g(x)\}$ is δ gp-closed in X .*

Proof. Let $E = \{x \in X : f(x) = g(x)\}$ and $x \notin (X \setminus E)$. Then $f(x) \neq g(x)$. Since Y is Hausdorff, there exist open sets V and W of Y such that $f(x) \in V$, $g(x) \in W$ and $V \cap W = \phi$, hence $\text{int}(\text{cl}(V)) \cap \text{int}(\text{cl}(W)) = \phi$. Since f and g are almost δ gp-continuous, there exist $G, H \in \delta\text{GPO}(X, x)$ such that $f(G) \subseteq \text{int}(\text{cl}(V))$ and $g(H) \subseteq \text{int}(\text{cl}(W))$. Now, put $U = G \cap H$, then $U \in \delta\text{GPO}(X, x)$ and $f(U) \cap g(U) \subseteq \text{int}(\text{cl}(V)) \cap$

$\text{int}(\text{cl}(W)) = \phi$. Therefore, we obtain $U \cap E = \phi$ and hence $x \notin \delta\text{gpcl}(E)$ then $E = \delta\text{gpcl}(E)$. Since X is δgp -additive, E is δgp -closed in X . \square

Definition 3.2. A space X is called δgp -compact if every cover of X by δgp -open sets has a finite subcover.

Definition 3.3. A subset M of a space X is said to be δgp -compact relative to X if every cover of M by δgp -open sets of X has a finite subcover.

Theorem 3.19. If $f: X \rightarrow Y$ is almost δgp -continuous and K is δgp -compact relative to X , then $f(K)$ is N -closed relative to Y .

Proof. Let $\{A_\alpha: \alpha \in \Omega\}$ be any cover of $f(K)$ by regular open sets of Y . Then $\{f^{-1}(A_\alpha): \alpha \in \Omega\}$ is a cover of K by δgp -open sets of X . Hence there exists a finite subset Ω_o of Ω such that $K \subset \cup\{f^{-1}(A_\alpha): \alpha \in \Omega_o\}$. Therefore, we obtain $f(K) \subset \{A_\alpha: \alpha \in \Omega_o\}$. This shows that $f(K)$ is N -closed relative to Y . \square

Corollary 3.1. If $f: X \rightarrow Y$ is an almost δgp -continuous surjection and X is δgp -compact and δgp -additive, then Y is nearly compact.

Lemma 3.1. Let X be δgp -compact. If $A \subset X$ is δgp -closed, then A is δgp -compact relative to X .

Proof. Let $\{B_\alpha: \alpha \in \Omega\}$ be a cover of N by δgp -open sets of X . Note that $(X-N)$ is δgp -open and that the set $(X-N) \cup \{B_\alpha: \alpha \in \Omega\}$ is a cover of X by δgp -open sets. Since X is δgp -compact, there exists a finite subset Ω_o of Ω such that the set $(X-N) \cup \{B_\alpha: \alpha \in \Omega_o\}$ is a cover of X by δgp -open sets in X . Hence $\{B_\alpha: \alpha \in \Omega_o\}$ is a finite cover of N by δgp -open sets in X . \square

Theorem 3.20. If the graph function $g: X \rightarrow X \times Y$ of $f: X \rightarrow Y$, defined by $g(x) = (x, f(x))$ for each $x \in X$ is almost δgp -continuous Then f is almost δgp -continuous.

Proof. Let $N \in RO(Y)$, then $X \times N \in RO(X \times Y)$. As g is almost δgp -continuous, $f^{-1}(N) = g^{-1}(X \times N) \in \delta\text{GPO}(X)$. \square

Theorem 3.21. If the graph function $g: X \rightarrow X \times Y$ of $f: X \rightarrow Y$, defined by $g(x) = (x, f(x))$ for each $x \in X$. If X is a submaximal space and δgp -additive, then g is almost δgp -continuous if and only if f is almost δgp -continuous.

Proof. We only prove the sufficiency. Let $x \in X$ and $W \in \text{RO}(X \times Y)$. Then there exist regular open sets U_1 and V in X and Y , respectively such that $U_1 \times V \subset W$. If f is almost δ gp-continuous, then there exists a δ gp-open set U_2 in X such that $x \in U_2$ and $f(U_2) \subset V$. Put $U = (U_2 \cap U_1)$. Then U is δ gp-open and $g(U) \subset U_1 \times V \subset W$. Thus g is almost δ gp-continuous. \square

Recall that for a function $f: X \rightarrow Y$, the subset $G_f = \{(x, f(x)) : x \in X\} \subset X \times Y$ is said to be graph of f .

Definition 3.4. A graph G_f of a function $f: X \rightarrow Y$ is said to be strongly δ gp-closed if for each $(p, q) \notin G_f$, there exist $U \in \delta\text{GPO}(X, p)$ and $V \in \text{RO}(Y, q)$ such that $(U \times V) \cap G_f = \phi$.

Lemma 3.2. For a graph G_f of a function $f : X \rightarrow Y$, the following properties are equivalent:

- (i) G_f is strongly δ gp-closed in $X \times Y$;
- (ii) For each $(p, q) \notin G_f$, there exist $U \in \delta\text{GPO}(X, p)$ and $V \in \text{RO}(Y, q)$ such that $f(U) \cap V = \phi$.

Theorem 3.22. Let $f: X \rightarrow Y$ have a strongly δ gp-closed graph G_f . If f is injective, then X is δ gp- T_1 .

Proof. Let $x_1, x_2 \in X$ with $x_1 \neq x_2$. Then $f(x_1) \neq f(x_2)$ as f is injective so that $(x_1, f(x_2)) \notin G_f$. Thus there exist $U \in \delta\text{GPO}(X, x_1)$ and $V \in \text{RO}(Y, f(x_2))$ such that $f(U) \cap V = \phi$. Then $f(x_2) \notin f(U)$ implies $x_2 \notin U$ and it follows that X is δ gp- T_1 . \square

Theorem 3.23. (i) If $f: X \rightarrow Y$ is almost δ gp-continuous and $g: Y \rightarrow Z$ is R-map, then $(g \circ f): X \rightarrow Z$ is almost δ gp-continuous.

(ii) If $f: X \rightarrow Y$ is δ gp-continuous and $g: Y \rightarrow Z$ is almost continuous, then $(g \circ f): X \rightarrow Z$ is almost δ gp-continuous.

(iii) If $f: X \rightarrow Y$ is δ gp-irresolute and $g: Y \rightarrow Z$ is almost δ gp-continuous, then $(g \circ f): X \rightarrow Z$ is almost δ gp-continuous.

Proof. (i) Let $N \in \text{RO}(Z)$. Then $g^{-1}(N) \in \text{RO}(Y)$ since g is R-map. The almost δ gp-continuity of f implies $f^{-1}[g^{-1}(N)] = (g \circ f)^{-1}(N) \in \delta\text{GPO}(X)$.

Hence $g \circ f$ is almost δ gp-continuous.

The proofs of (ii) and (iii) are similar to (i). \square

Definition 3.5. [33] A function $f: X \rightarrow Y$ is called pre δ gp-closed if $f(U) \in \delta\text{GPC}(Y)$ for every $U \in \delta\text{GPC}(X)$.

Theorem 3.24. *If $f: X \rightarrow Y$ is a pre δ gp-open surjection and $g: Y \rightarrow Z$ is a function such that $g \circ f: X \rightarrow Z$ is almost δ gp-continuous, then g is almost δ gp-continuous.*

Proof. Let $y \in Y$ and $x \in X$ such that $f(x) = y$. Let $G \in \text{RO}(Z, (g \circ f)(x))$. Then there exists $U \in \delta\text{GPO}(X, x)$ such that $g(f(U)) \subset G$. Since f is pre δ gp-open in Y , we have that g is almost δ gp-continuous at y .

Let A be a subset of X . Then A is said to be H -closed [35] relative to X if for every cover $\{B_i: i \in \Omega\}$ of A by open sets of X , there exists a finite subset Ω_o of Ω such that $A \subset \cup\{\text{cl}(B_i) : i \in \Omega_o\}$. \square

Definition 3.6. *A function $f: X \rightarrow Y$ is said to be δ gp*-continuous if for each $p \in X$ and each $N \in \mathcal{O}(Y, f(p))$, there exists $M \in \delta\text{GPO}(X, p)$ such that $f(M) \subset N$.*

Theorem 3.25. *If $f: X \rightarrow Y$ is δ gp*-continuous and K is δ gp-compact relative to X , then $f(K)$ is H -closed relative to Y .*

Proof. Similar to the proof of Theorem 3.19 \square

Theorem 3.26. *If for each pair of distinct points p and q in a space X , there exists a function f of X into a Hausdorff space Y such that*

(i) $f(p) \neq f(q)$,

(ii) f is δ gp*-continuous at p and

(iii) almost δ gp-continuous at q , then X is δ gp-Hausdorff.

Proof. Since Y is Hausdorff, there exist open sets W_1 and W_2 of Y such that $f(p) \in W_1$, $f(q) \in W_2$ and $W_1 \cap W_2 = \emptyset$, hence $\text{cl}(W_1) \cap \text{int}(\text{cl}(W_2)) = \emptyset$. Since f is δ gp*-continuous at p , there exists $U_1 \in \delta\text{GPO}(X, p)$ such that $f(U_1) \subset \text{cl}(W_1)$. Since f is almost δ gp-continuous at q , there exists $U_2 \in \delta\text{GPO}(X, q)$ such that $f(U_2) \subset \text{int}(\text{cl}(W_2))$. Therefore, we obtain $U_1 \cap U_2 = \emptyset$. This shows that X is δ gp-Hausdorff. \square

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